DANIEL MARTINEZ

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PROFESSIONAL EXPERIENCE

Caterpillar, Inc. (LanceSoft), Peoria, IL

R&D Robotics Engineer – Automation Systems Development Team

- Responsible for developing and demonstrating automation technologies, which are often used in conjunction with information systems, remote control, semi-autonomous, and fully autonomous machine control systems.
- Worked in tandem with senior project lead on the development and application of positioning and mission planning technologies and systems.
- Developed and implemented pose estimation algorithms.
- Successfully planned and executed field testing of pose estimation system at company proving grounds.
- Developed sensor interface and logging applications.
- Supported existing autonomy software by learning and documenting existing algorithms.
- Gained extensive experience with Perception, Positioning, and Mission Planning on mobile robotic platforms.
- Developed software for use in a distributed architecture system (similar to ROS), with an Object-Oriented codebase (C++, C), in a Linux environment.
- Worked extensively with the selection, implementation, and testing of high end IMU and GPS sensor components as part of the development of a Strapdown Inertial Navigation System.
- Played a vital role in significantly improving pose system accuracy.
- Became the team's rapid prototyping expert, helping to quickly model and 3D print custom mounts, brackets, and housings in support of ongoing research projects.

United States Navy, MTS- 626 Charleston, SC	2002-2007
Naval Nuclear Power Training Unit (NPTU)	2002-2007

Nuclear Power Plant Operator, Senior Reactor Operator – Instructor

- Highly skilled reactor operator and maintenance technician with hands-on and supervisory experience.
- Crew's expert on the Engineered Safety Features and Supplemental water injection systems.
- Developed an extensive knowledge in radiological controls and APD maintenance as the crew's leading CMG petty officer. Selected as lead reactor operator for drill evolutions.
- Demonstrated outstanding reactor system aptitude and troubleshooting skills on the system and component level.

Teamwork

- Extensive experience in operating as part of a watch team in all aspects of U.S. Navy submarine reactor and steam plant operation.
- Assigned and scheduled technicians according to skill and experience.
- Extensive experience supervising personnel in operations, maintenance, troubleshooting, and repair.

Testing

- Tested, calibrated, maintained, and repaired electronic and hydraulic-electric systems that support reactor plant operations.
- Operated, maintained, and repaired reactor instrumentation and control systems.

Training

- Selected among many peers to become a Nuclear Power Instructor at NPTU Charleston
- Provided theoretical and hands-on training to in all aspects of the safe operation of naval nuclear power plants

Jun. 2015 – Present

EDUCATION	
Georgia Institute of Technology, Atlanta, GA	
Master of Science in Computer Science	Aug 2016 – Dec 2018
Specialization Track: Computer Vision and Robotics	
Florida International University, Miami, FL	
Bachelor of Science in Mechanical Engineering (BSME)	2015
Professional Certificate in Robotics Engineering	2015
Overall GPA 3.6/4.0, Honors and Awards Dean's List	
Relevant Courses Circuits, CAD, Programming for ME, Mechatronics, Sensors & and Control of Robots, Robot Design, Robotics Undergraduate Research	Signal Processing, Simulation Software, Modeling
Navy Schools, Charleston, SC	2007
Naval Leadership Development, Self-Contained Breathing Apparatus and Respirate Naval Nuclear Power School, Naval Nuclear Power Training Unit, Electronics Tech Honors and Awards COs letter (1), Good conduct (1)	or Qualification, Core Maintenance Group (CMG), hnician "A" School, Basic Firefighting.
AFFILIATIONS	
Engineering Honors Society- Tau Beta Pi	2013–Present
Central Illinois Robotics Club (CIRC)	2015–Present

PROFESSIONAL DEVELOPMENT

University of Pennsylvania Robotics Specialization (Coursera)

University of Pennsylvania's Robotics Specialization series consisted of sixcourses designed to expose students to a wide array of topics in the Robotics field. Some of the areas covered in the course work included robot flight and movement, visual perception, estimation, navigation, and control theory. The course concluded with a hands-on capstone project.

PROJECTS

UPenn Robotics Capstone Project

The project goal was to develop an autonomous mobile robotic platform that featured an embedded Linux device running ROS, a motor controller, an IMU, and a camera. With April Tag measurements and a known map, the rover was able to successfully localize, plan a path, navigate that path, and maintain an up-to-date pose estimate, all autonomously.

BSME Senior Design Project

Designed, built, and programed a remotely operated submersible vehicle (ROV) as a member of a three person team. I was responsible for planning and implementing the control code in MATLAB.

CONFERENCE PAPERS AND PRESENTATIONS

Daniel Martinez, Daniella Motro, Santiago Nino, Sabri Tosunoglu. *Wireless and Autonomous Guide Platform to Assist the Visually Impaired Through Unfamiliar Spaces*. Proceedings of the 28th Florida Conference on Recent Advances in Robotics, FCRAR 2015, Melbourne, Florida, May 14-15, 2015.

Daniel Martinez, Ryan Wright, Edgar English. *Remotely Operated Underwater Vehicle*. Proceedings of the 27th Florida Conference on Recent Advances in Robotics, FCRAR 2014, Miami, Florida, May 8-9, 2014.

Daniel Martinez. *Fire Reconnaissance Rover*. Proceedings of the 27th Florida Conference on Recent Advances in Robotics, FCRAR 2014, Miami, Florida, May 8-9, 2014.

SKILLS

Software: Linux, ROS, MATLAB, Eclipse, SolidWorks, Simulink, Labview, OpenCV, Visual Studio, MS Office Suite. **Manufacturing and Machining:** 3D printing, mills, lathes, band saws, grinders, shears, drill presses, soldering, etc. **Programming Languages:** C/C++, Python, MATLAB; **Spoken Languages:** Fluent in English, Fluent in Spanish